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George Plosker

IEEE Client Services Manager

September 2015







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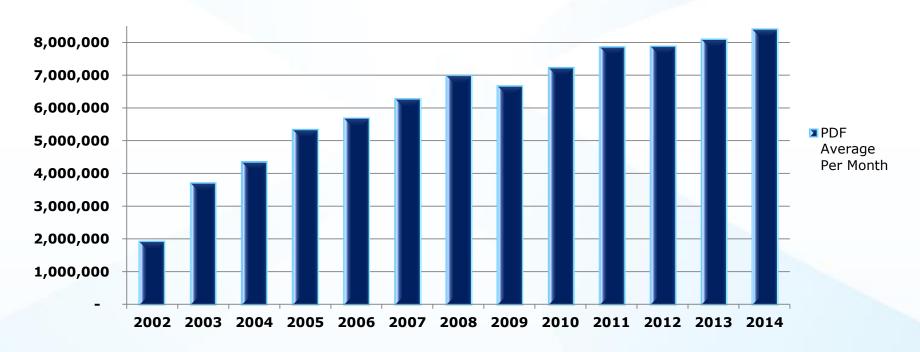




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- IEEE Cloud Computing
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2003 - 2013: >50 new journals added









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- IEEE Trans. on Big Data
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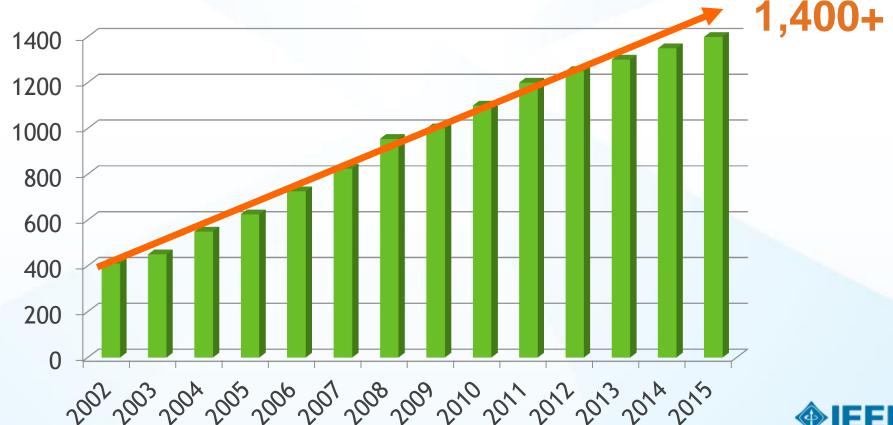




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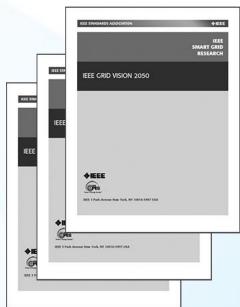
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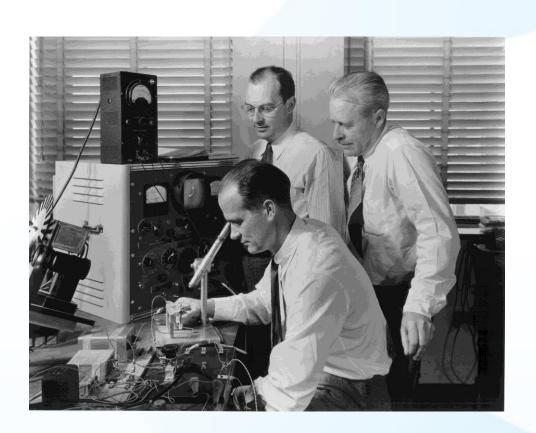




Historic content from BLTJ

Volume 28, 1949

- Invention of the first Transistor
- Fundamental building block of modern electronic devices
- Research won a Nobel Prize in 1947
 - William Shockley
 - John Bardeen
 - Walter Brattain





Historic content from BLTJ



Volume 42, 1963

- Telstar
- World's first active communications satellite
- Was able to transmit television signals and collect data on radiation in space



Other Seminal Papers from Bell Labs

- The Unix-Time Sharing System (1978)
 - The original paper describing the Operating System
- A mathematical theory of communication (1948)
 - Defined the field of information theory
- In-Band Single-Frequency Signaling (1954)
 - Enabled the famous "Blue Boxes"
- Number One Electronic Switching System (1964)
 - The first stored-program telephone switch, a technological marvel of its day
- The Cellular Concept (1978)
 - Plan to create mobile telephone service on a large scale

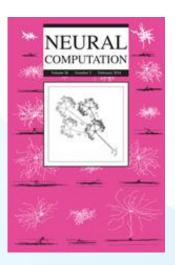




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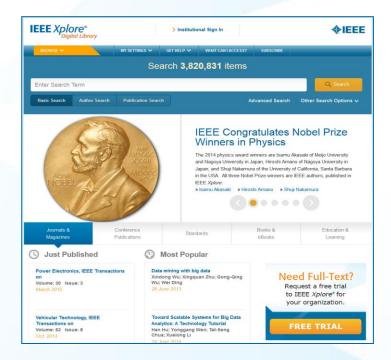




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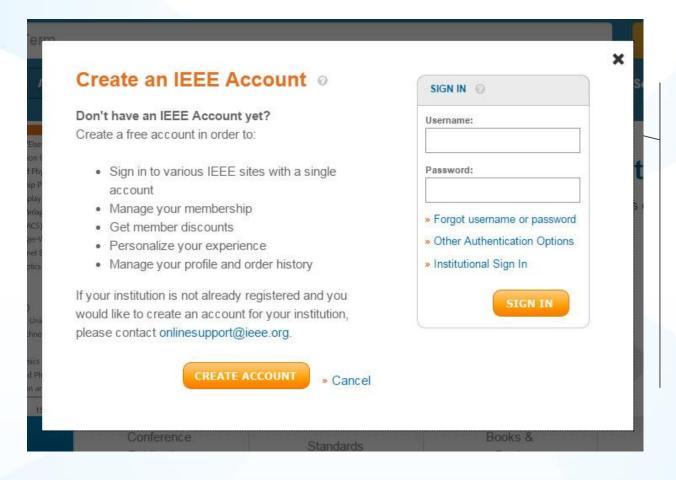
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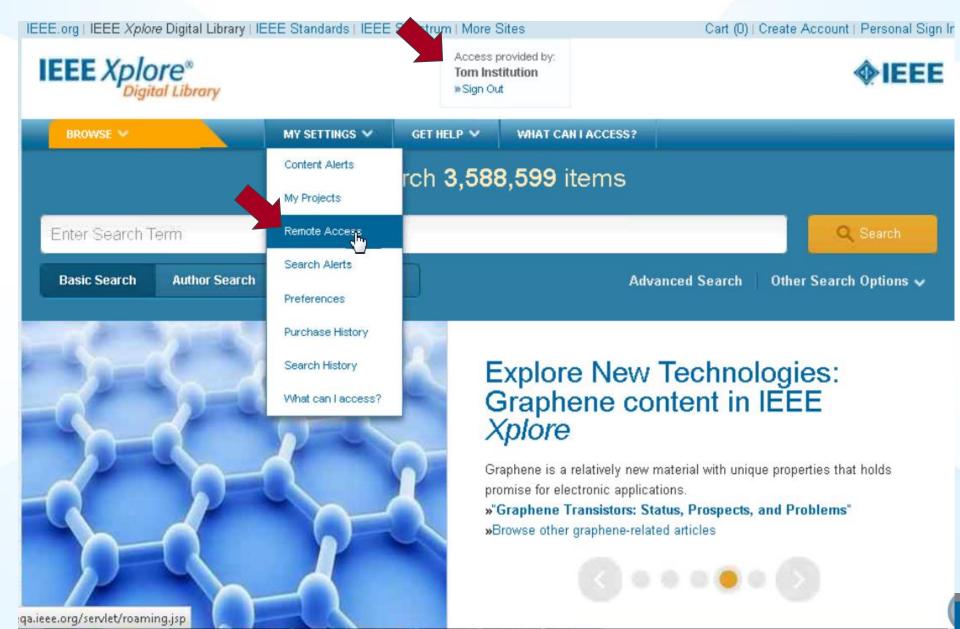
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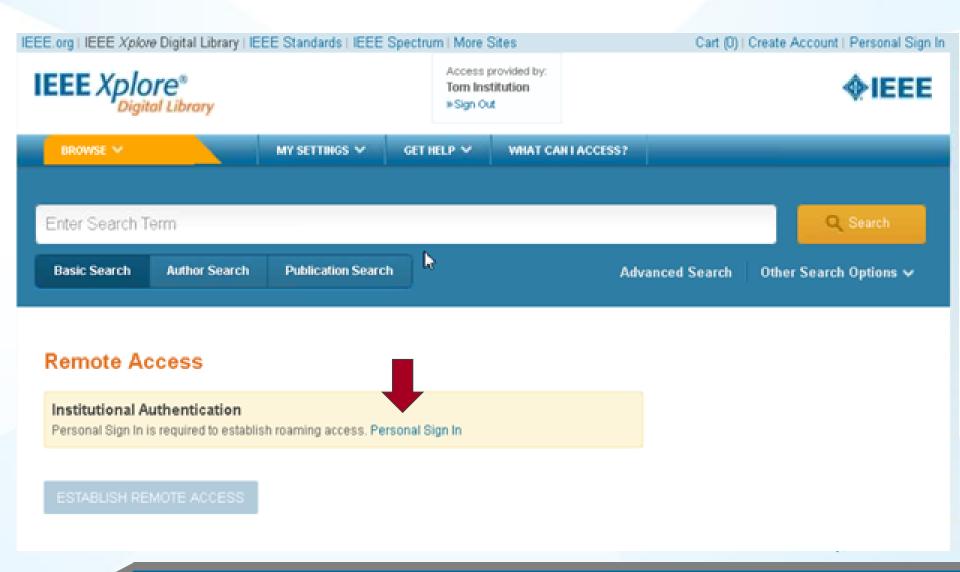
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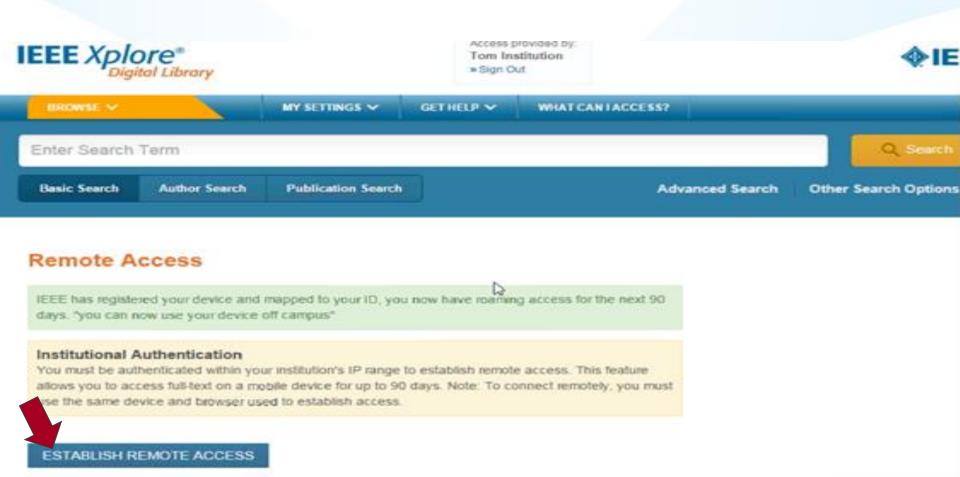
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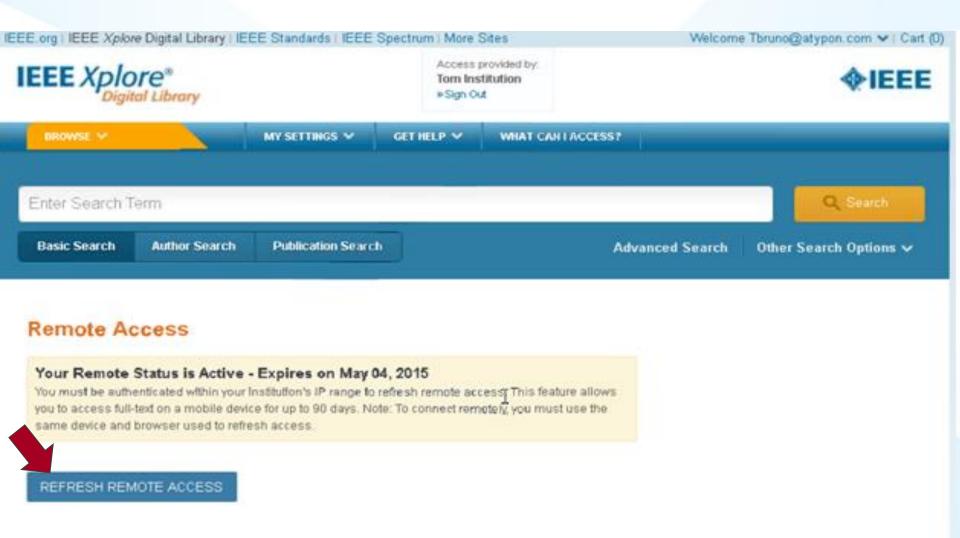


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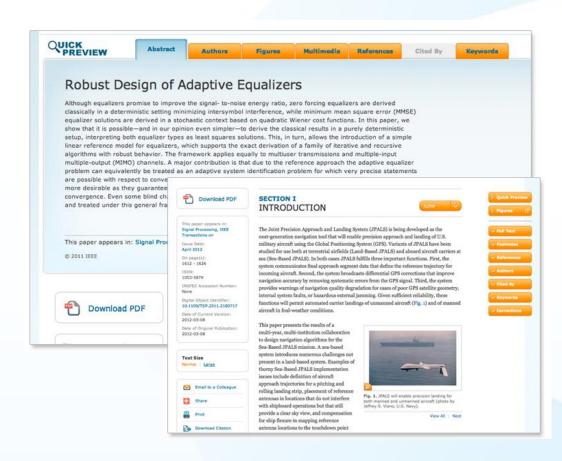
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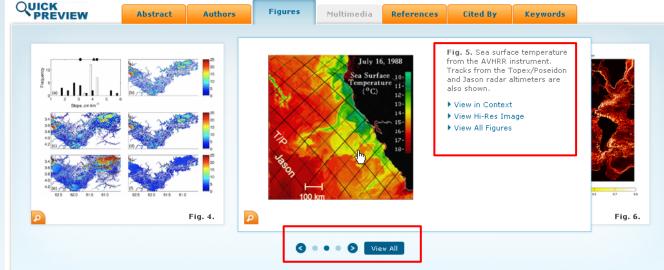
Satellite altimetry measurements of ocean surface the 1980s: Seasat, Geosat, ERS-1, ERS-2, TOPEX/Jason-2. These measurements have led to dramatic of oceanography [33]. For instance, the TOPEX/Podemonstrated an average rise of global sea level of

TOPEX/Poseidon OST measurements level and their relations to the heat stor TOPEX/Poseidon were used to study tlevent in historical context [36]. Becaus between the OST variability and the phroST measurements into ocean circulating global ocean circulation patterns [38]. (scientific predictive capabilities. For in



JUMP





3.1 Formulation of Feature Combination

As discussed in Section 2, we treat the set of all possible appearances of the image patch surrounding a keypoint as a class. Therefore, given the patch surrounding a keypoint detected in an image, our task is to assign it to the most likely class. Let c_i , $i=1,\ldots,H$, be the set of classes and let f_j , $j=1,\ldots,N$, be the set of binary features that will be calculated over the patch that we are trying to classify. Formally, we are looking for

$$\hat{c_i} = \mathop{\mathrm{argmax}}_{c_i} \ P(C = c_i \mid f_1, f_2, \dots, f_N),$$

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where C is a random variable that represents the class. Bayes' formula yields

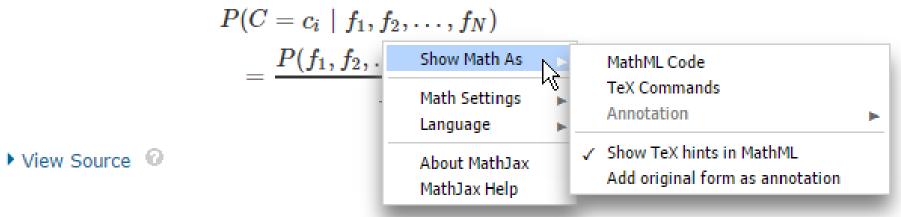
$$egin{aligned} P(C = c_i \mid f_1, f_2, \dots, f_N) \ &= rac{P(f_1, f_2, \dots, f_N \mid C = c_i) P(C = c_i)}{P(f_1, f_2, \dots, f_N)}. \end{aligned}$$

Assuming a uniform prior P(C), since the denominator is simply a scaling factor that is independent from the class, our problem reduces to finding

$$\hat{c_i} = \operatorname*{argmax}_{c_i} P(f_1, f_2, \ldots, f_N \mid C = c_i).$$
 (1)



where C is a random variable that represents the class. Bayes' formula yields

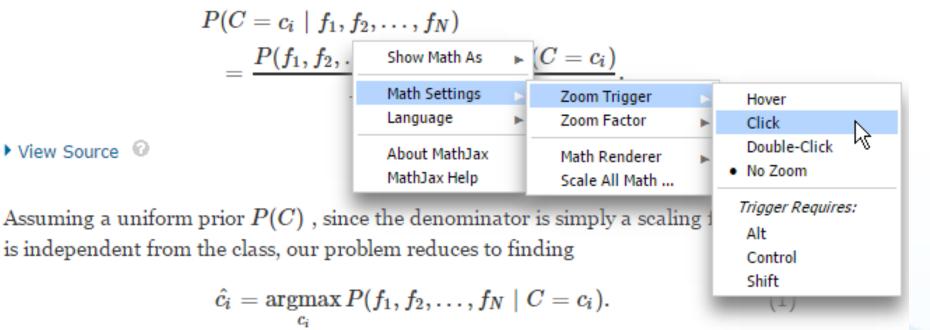


Assuming a uniform prior P(C), since the denominator is simply a scaling factor that is independent from the class, our problem reduces to finding



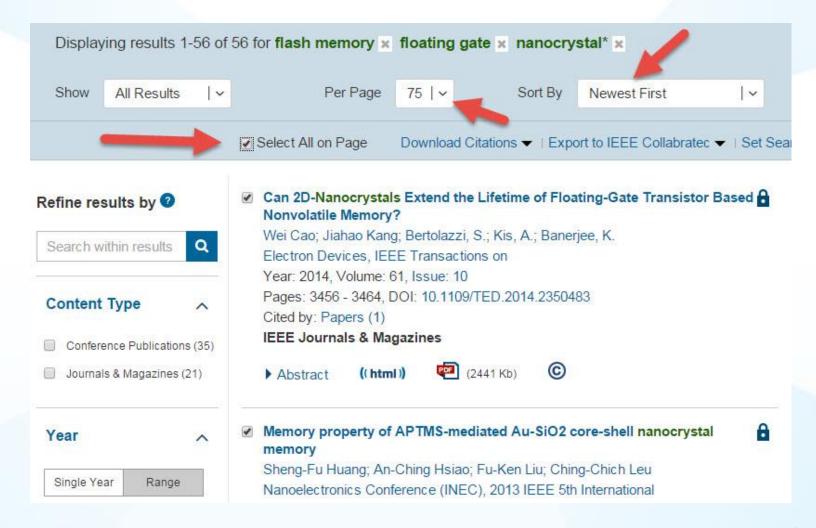
where C is a random variable that represents the class. Bayes' formula yields

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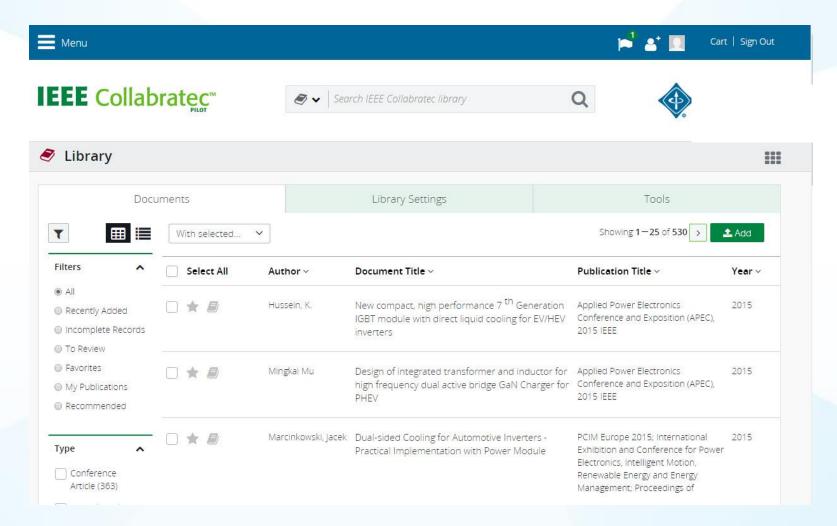
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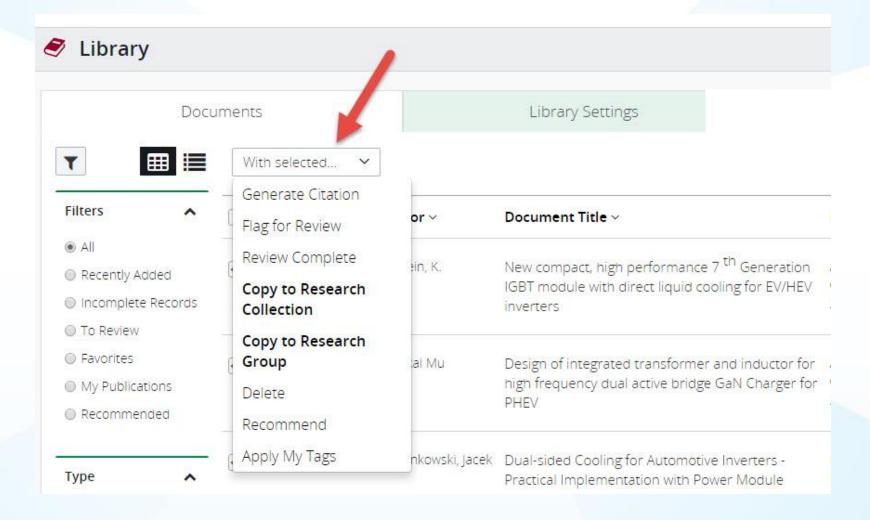
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Ganesh, Anand; Munsil, Donald J.; Sullivan, Gary J.; Evans, Glenn F.; Sadhwani, Shyam; Estrop, Stephen J., "Accelerated video encoding", Patent No. 8654842

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Inventors:

Ganesh, Anand ; Munsil, Donald J. ; Sullivan, Gary J. ; Evans, Glenn F. ; Sadhwani, Shyam ; Estrop, Stephen J.

Abstract:

A video encoding acceleration service to increase one or more of the speed and quality of video encoding is described. The service acts as an intermediary between an arbitrary video encoder computer program application and arbitrary video acceleration hardware. The service receives one or more queries from the video encoder to identify implementation specifics of the video acceleration hardware. The service interfaces with the video acceleration hardware to obtain the implementation specifics. The service communicates the implementation specifics to the video encoder. The implementation specifics enable the video encoder to: (a) determine whether one or more of speed and quality of software encoding operations associated with the video encoder can be increased with implementation of a pipeline of one or more supported encoding pipeline configurations and capabilities, and (b) implement the pipeline by interfacing with the service.

Assignee:

MICROSOFT CORP

Filing Date:

February 09, 2007

Grant Date:

February 18, 2014

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Patent Classes:

Current U.S. Class:

375240120, 375240220, 375240250, 382232000

Current International Class:

H04N0071200000

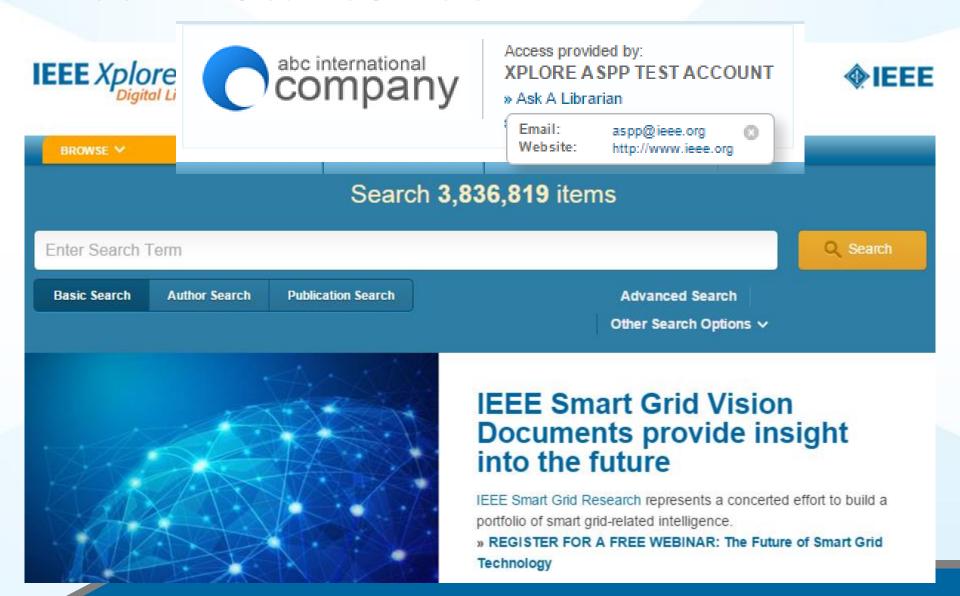


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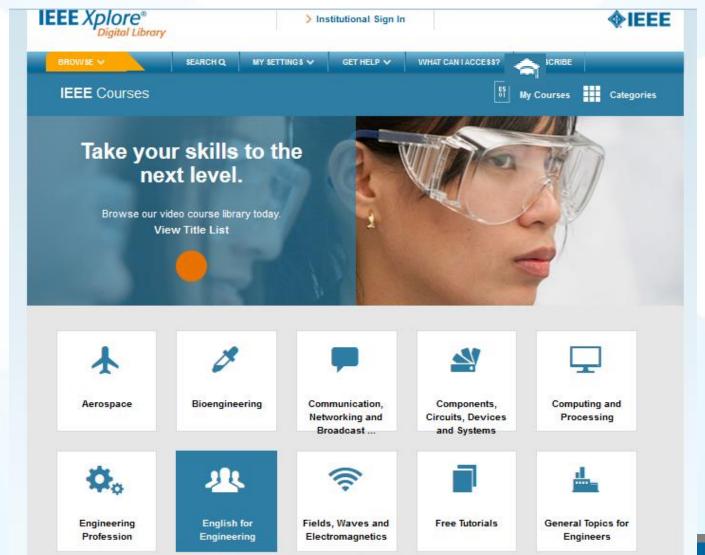


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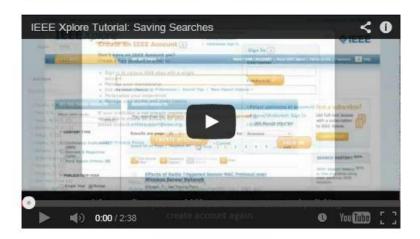
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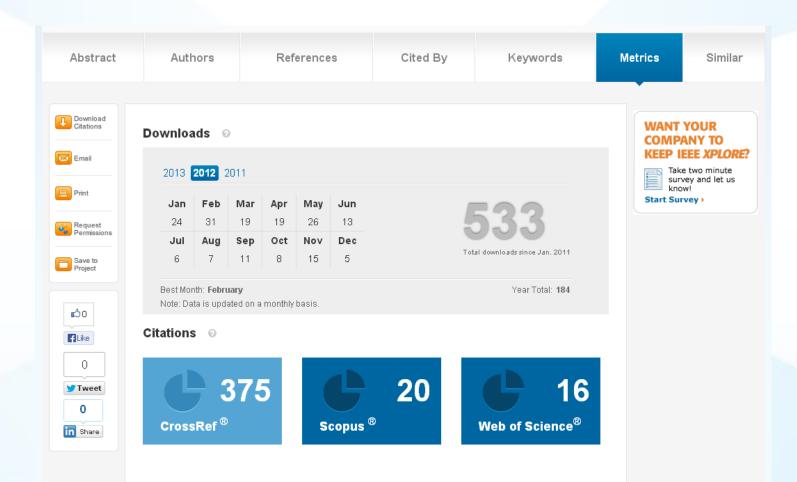
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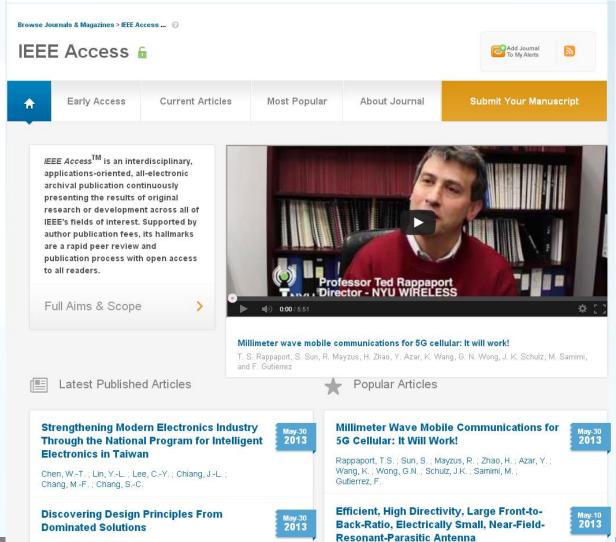


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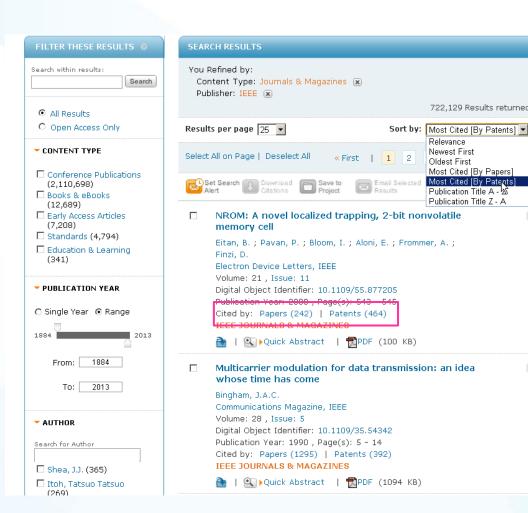


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The Surface Water and Ocean Topography Mission: Observing Terrestrial Surface Water and Oceanic Submesoscale Eddies

The elevation of the ocean surface has been measured for over two decades from spaceborne altimeters. However, existing altimeter measurements are not adequate to characterize the dynamic variations of most inland water bodies, nor of ocean eddies at scales of less than about 100 km, notwithstanding that such eddies play a key role in ocean circulation and climate change. For terrestrial hydrology, in situ and spaceborne measurements of water surface elevation form the basis for estimates of water storage change in lakes, reservoirs, and wetlands, and of river discharge. However, storage in most inland water bodies, e.g., millions of Arctic lakes, is not readily measured using existing technologies. A solution to the needs of both surface water hydrology and physical oceanography communities is the measurement of water elevations along rivers, lakes, streams, and wetlands and over the ocean surface using swath altimetry. The proposed surface water and ocean topography (SWOT) mission will make such measurements. The core technology for SWOT is the Ka-band radar interferometer (KaRIN), which would achieve spatial resolution on the order of tens of meters and centimetric vertical precision when averaged over targets of interest. Average revisit times will depend upon latitude, with two to four revisits at low to mid latitudes and up to ten revisits at high latitudes per ~20-day orbit repeat period.

This paper appears in: Proceedings of the IEEE, Issue Date: May 2010, Written by: Durand, M.; Lee-Lueng Fu; Lettenmaier, D.P.; Alsdorf, D.E.; Rodriguez, E.; Esteban-Fernandez, D.

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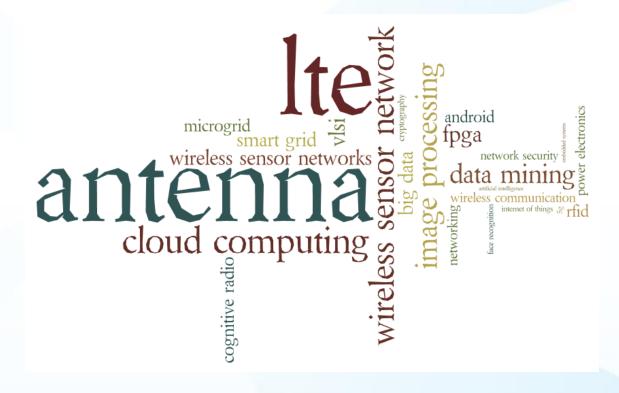
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